

Eigenvectors and Eigenvalues.

Main question:

► Let $T: V \rightarrow V$ be a linear operator on a (finite dimensional) vector space.

► Let $\mathcal{B} = \{\bar{b}_1, \bar{b}_2, \dots, \bar{b}_n\}$ be a basis for V .

► The matrix associated with T with respect to \mathcal{B} is given

by

$$M_T^{\mathcal{B}} = \left([T(\bar{b}_1)]_{\mathcal{B}} \cdots [T(\bar{b}_n)]_{\mathcal{B}} \right)$$

Is it possible to find some basis C of V such that M_T^C is as simple as possible?

↳ Diagonal

Recall that:

$$M_T^C = P_{C \leftarrow B} M_T^B P_{B \leftarrow C}$$

Goal: Find a basis C

(when possible) such that M_T^C

is diagonal

$T: V \rightarrow V$

$$M_T^C = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \dots & \\ & & & \lambda_n \end{pmatrix}_{n \times n}$$

$$\dim V = n$$

That is, if $C = \{\bar{c}_1, \bar{c}_2, \dots, \bar{c}_n\}$

$$M_T^C = \left([T(\bar{c}_1)]_C \quad [T(\bar{c}_2)]_C \quad \dots \quad [T(\bar{c}_n)]_C \right)$$

$$= \begin{pmatrix} \lambda_1 & & \\ & \dots & \\ & & \lambda_n \end{pmatrix}$$

► $[T(\bar{c}_1)]_C = \begin{pmatrix} \lambda_1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \Rightarrow T(\bar{c}_1) = \lambda_1 \bar{c}_1$

$$[T(\bar{c}_2)]_C = \begin{pmatrix} 0 \\ \lambda_2 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \Rightarrow T(\bar{c}_2) = \lambda_2 \bar{c}_2$$

$$[T(\bar{c}_n)]_C = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \lambda_n \end{pmatrix} \Rightarrow T(\bar{c}_n) = \lambda_n \bar{c}_n$$

Eigenvalues and Eigenvectors.

Definition. Let $T: V \rightarrow V$ be a linear mapping.

► An eigenvector of T is a non zero vector $\bar{x} \in V$ such that

$$T(\bar{x}) = \lambda \bar{x} \quad \bar{x} \neq \bar{0}$$

for some scalar λ .

eigenvector:

- vector propio
- autovector

► The scalar λ is called the eigenvalue associated with \bar{x} .

$$\begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & 0 & \\ & & & \lambda_3 \end{pmatrix}$$

Eigenvalues are allowed to be zero.

Example. Let $T: \mathbb{C}^2 \rightarrow \mathbb{C}^2$ be defined

by

$$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} -y \\ x \end{bmatrix}$$

$$\mathbb{C}^2 = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x, y \in \mathbb{C} \right\}$$

Eigenvalues? $\lambda_1 = i$, $\lambda_2 = -i$

$$\lambda_1 = i \quad T \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x \end{bmatrix} = i \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{array}{l} \boxed{-y = ix} \\ i \rightarrow x = iy \end{array} \Rightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \alpha \begin{bmatrix} i \\ 1 \end{bmatrix} \quad \alpha \in \mathbb{R}$$

$$ix = -y$$

$$-y = i(iy) = -y \Rightarrow 0 = 0$$

$\lambda_2 = -i$ if $\begin{bmatrix} x \\ y \end{bmatrix}$ is an eigenvector then

$$T \begin{bmatrix} x \\ y \end{bmatrix} = -i \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} -y \\ x \end{bmatrix} = -i \begin{bmatrix} x \\ y \end{bmatrix}$$

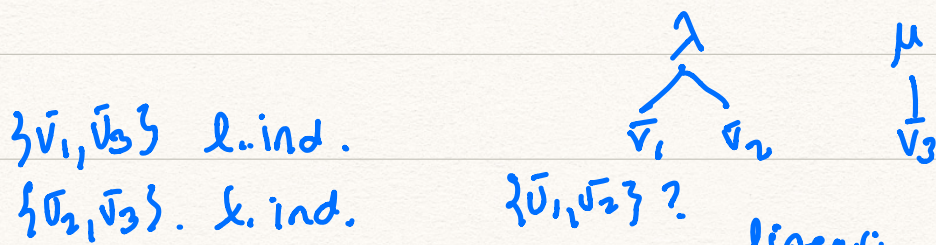
$$\begin{aligned} -y &= -ix \Rightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \beta \begin{bmatrix} -i \\ 1 \end{bmatrix} \\ x &= -iy \leftarrow \cdot -i & x &= -iy = -i\beta \\ -ix &= +i(i)y = -y & y &= \beta \end{aligned}$$

Basis of \mathbb{C}^2 formed totally by eigenvectors
of $T: \mathbb{C} = \left\{ \begin{pmatrix} i \\ i \end{pmatrix}, \begin{pmatrix} -i \\ i \end{pmatrix} \right\}$

$$M_T^{\mathbb{C}} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

$\dim \mathbb{C}^2 = 2$, 2 distinct eigenvalue

$\dim V = 5$, 3 distinct eigenvalues



linear:

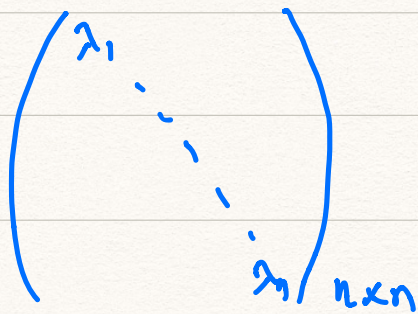
- function
- mapping.
- transformation
- operator.

Theorem. Let $T: V \rightarrow V$ be a linear operator. Let $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_m$ be eigenvectors associated with distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_m$ ($\lambda_i \neq \lambda_j$ when $i \neq j$).

Then $\{\bar{x}_1, \bar{x}_2, \dots, \bar{x}_m\}$ is a linearly independent set.

Corollary Let $T: V \rightarrow V$ be a linear operator.

Then T has at most $\dim V$ eigenvectors.
"n" \swarrow lin. ind.



at most n distinct eigenvalues

Theorem \Downarrow

at most n lin. ind. eigenvectors

Example Let V be the (infinite dimensional) vector space of functions with derivatives of any order.

Let $T: V \rightarrow V$ be a linear operator defined by $T[f] = f'$.

For each $\lambda \in \mathbb{R}$, consider the function $f_\lambda(t) = e^{\lambda t}$. \leftarrow eigenvectors of T

$$T[e^{\lambda t}] = \frac{d}{dt} e^{\lambda t} = \lambda e^{\lambda t} \quad T[f_\lambda] = \lambda f_\lambda$$

$$\lambda_1 \neq \lambda_2 \quad \{e^{\lambda_1 t}, e^{\lambda_2 t}\} \text{ lin ind.}$$

Example. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator defined by

$$T(\bar{x}) = \begin{pmatrix} 4 & -1 & 6 \\ 2 & 1 & 6 \\ 2 & -1 & 8 \end{pmatrix} \bar{x} \quad \leftarrow M_T^{e_3, e_3} \quad 2, 9$$

► $\lambda_1 = 2$ is an eigenvalue of T with associated eigenvectors

$$\begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -2 \\ 2 \\ 1 \end{pmatrix}$$

$\underbrace{\hspace{10em}}_{\left(\frac{1}{3}\right) + \left(-\frac{3}{0}\right)}$

► $\lambda_2 = 9$ is an eigenvalue of T with associated eigenvector $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$.

$$\lambda: \begin{matrix} T(\bar{x}) = \lambda \bar{x} \\ T(\bar{y}) = \lambda \bar{y} \end{matrix} \quad \leftarrow$$

$$T(\alpha \bar{x} + \beta \bar{y}) = \alpha T(\bar{x}) + \beta T(\bar{y}) = \alpha \lambda \bar{x} + \beta \lambda \bar{y}$$

$$T(\alpha \bar{x} + \beta \bar{y}) = \lambda (\alpha \bar{x} + \beta \bar{y})$$

$$T \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 4 & -1 & 6 \\ 2 & 1 & 6 \\ 2 & -1 & 8 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$$

$$T \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 & -1 & 6 \\ 2 & 1 & 6 \\ 2 & -1 & 8 \end{pmatrix} \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -6 \\ 0 \\ 2 \end{pmatrix} = 2 \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}$$

$$E_2 = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$E_1 = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

Definition. Let $T: V \rightarrow V$ be a linear operator. For each eigenvalue λ of T , we define the set

$$E_\lambda = \text{Span} \{ \bar{x} : T(\bar{x}) = \lambda \bar{x} \} \subseteq V$$

Called the eigenspaces associated with λ .

Theorem E_λ is a subspace of V .

We call E_λ the eigenspace associated with λ .

Theorem* Let $T: V \rightarrow V$ be a linear operator, and let M_T^B be its associated matrix with respect to a basis B .

For each eigenvalue λ of T : $T(\bar{x}) = \lambda \bar{x}$

$$E_\lambda = \text{Ker}(T - \lambda I_d)$$

$$(\text{Nul}(M_T^B - \lambda I_n))$$

$$T(\bar{x}) = \lambda \bar{x}$$

$$T(\bar{x}) - \lambda \bar{x} = \bar{0}$$

$$(T - \lambda I_d)(\bar{x}) = \bar{0}$$

$$\dim E_\lambda = \dim V - \text{Rank}(M_T^B - \lambda I_n)$$

λ is a root of the polynomial

$$\det(M_T^B - \lambda I_n)$$

degree $\dim V$

$$M_T^B [\bar{x}]_B - \lambda [\bar{x}]_B = \bar{0}$$

$$(M_T^B - \lambda I) [\bar{x}]_B = \bar{0}$$

$$T(\bar{x}) = \lambda \bar{x} \xrightarrow{B} [T(\bar{x})]_B = M_T^B [\bar{x}]_B = \lambda [\bar{x}]_B$$

\curvearrowright
 B

Definition. Let $T: V \rightarrow V$ be a linear operator and let $M_T^{\mathcal{B}}$ be its associated matrix with respect to a basis \mathcal{B} .

► The polynomial

$$\det(M_T^{\mathcal{B}} - \lambda I_n)$$

of degree $n = \dim V$ is called the characteristic polynomial of T (or of $M_T^{\mathcal{B}}$).

► $\det(M_T^{\mathcal{B}} - \lambda I_n) = 0$ is called the characteristic equation of T (or of $M_T^{\mathcal{B}}$).

Example Find the eigenvalues and eigenvectors of the linear mapping $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(\bar{x}) = A\bar{x}$ where

$$A = \begin{pmatrix} 2 & 3 \\ 3 & -6 \end{pmatrix}$$

Example Find the eigenvalues and eigenvectors of the linear mapping $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(\bar{x}) = A\bar{x}$

$$A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

Example Find the eigenvalues and eigenvectors of the linear mapping $T: \mathbb{R}^4 \rightarrow \mathbb{R}^4$ defined by $T(\bar{x}) = A\bar{x}$ where

$$A = \begin{pmatrix} 5 & -2 & 6 & -1 \\ 0 & 3 & -8 & 0 \\ 0 & 0 & 5 & 4 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Theorem. The characteristic polynomial of a linear operator is invariant under change of basis.

Multiplicity of eigenvalues

Example. $A = \begin{pmatrix} 2 & 2 & 3 \\ 0 & 2 & 2 \\ 0 & 0 & 2 \end{pmatrix}$

Example $A = \begin{pmatrix} 2 & 2 & 2 \\ 0 & -1 & -1 \\ 0 & 0 & 2 \end{pmatrix}$

Theorem Let $T: V \rightarrow V$ be a linear operator and let $p(x)$ be its characteristic polynomial.

For each eigenvalue λ ,

$$p(x) = (x - \lambda)^{m_\lambda} q(x), \quad q(\lambda) \neq 0$$

and $1 \leq \dim E_\lambda \leq m_\lambda$ where E_λ is the eigenspace associated with λ .

Diagonalizable linear mappings

Definition. A linear mapping $T: V \rightarrow V$ is diagonalizable if there exists a basis $B = \{\bar{b}_1, \bar{b}_2, \dots, \bar{b}_n\}$

of V made up entirely of eigenvectors of T . Consequently,

$$M_T^{B,B} = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix}$$

where $T(\bar{b}_i) = \lambda_i \bar{b}_i$, $i=1, 2, \dots, n$.

Theorem. A linear mapping $T: V \rightarrow V$ ($n = \dim V$) is diagonalizable if and only if T has n linearly independent eigenvectors.

Corollary. If $\lambda_1, \lambda_2, \dots, \lambda_k$ are distinct eigenvalues of a linear mapping $T: V \rightarrow V$, then T is diagonalizable if and only if

$$\dim E_{\lambda_1} + \dim E_{\lambda_2} + \dots + \dim E_{\lambda_k} = n.$$

► If and only if, for each eigenvalue λ with multiplicity m_λ , $\dim E_\lambda = m_\lambda$.

► If and only if, for each eigenvalue λ with multiplicity m_λ , there exist m_λ linearly independent eigenvectors associated with λ .

Corollary. If each eigenvalue of $T: V \rightarrow V$ has multiplicity 1, then T is diagonalizable.

Example If possible, diagonalize the linear mapping $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(\bar{x}) = A\bar{x}$ where

$$A = \begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix}$$

Example If possible, diagonalize the linear mapping $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(\bar{x}) = A\bar{x}$ where

$$A = \begin{pmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{pmatrix}$$

Example If possible, diagonalize the
the linear mapping $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined
by $T(\bar{x}) = A\bar{x}$ where $A = \begin{pmatrix} 5 & -8 & 1 \\ 0 & 0 & 7 \\ 0 & 0 & -2 \end{pmatrix}$